

A Derivation of the Steady-State MSE of RLS: Stationary and Nonstationary Cases

Phil Schniter

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Abstract

In this report we combine the approach of Yousef and Sayed [1] with that of Rupp and Sayed [2] to derive the steady-state mean-squared error (MSE) of the recursive least squares (RLS) algorithm in both stationary and non-stationary environments. Comparisons with the steady-state MSE of LMS are included.

1 Introduction

The recursive least squares (RLS) parameter update equation can be written as

$$\mathbf{w}(n) = \mathbf{w}(n-1) + \underbrace{\mathbf{P}(n)\mathbf{u}(n)}_{\mathbf{k}(n)} \underbrace{(d(n) - \mathbf{w}^H(n-1)\mathbf{u}(n))^*}_{\xi^*(n)}$$

where $\mathbf{P}(n)$ is the inverse of the deterministic autocorrelation matrix $\Phi(n)$

$$\begin{aligned} \mathbf{P}(n) &= \Phi^{-1}(n) \\ \Phi(n) &= \sum_{i=1}^n \lambda^{n-i} \mathbf{u}(i)\mathbf{u}^H(i) + \delta\lambda^n \mathbf{I} \end{aligned}$$

with $0 < \lambda \leq 1$. We assume a nonstationary environment with time-varying Wiener filter $\mathbf{w}_*(n)$ that evolves as a random walk:

$$\begin{aligned} d(n) &= \mathbf{w}_*^H(n-1)\mathbf{u}(n) + \xi_*(n) \\ \mathbf{w}_*(n) &= \mathbf{w}_*(n-1) + \mathbf{q}(n) \end{aligned} \tag{1}$$

$\xi_*(n)$ denotes the MMSE version of $\xi(n)$ which, due to the MMSE orthogonality principle, is uncorrelated with $\mathbf{u}(n)$:

$$\mathbb{E}\{\mathbf{u}(n)\xi_*(n)\} = \mathbf{0}$$

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Other statistical assumptions will be stated later.

We will make extensive use of the parameter error vector $\tilde{\mathbf{w}}(n)$, the a posteriori error $e_p(n)$, and the a priori error $e_a(n)$.

$$\begin{aligned}
\tilde{\mathbf{w}}(n) &:= \mathbf{w}_*(n) - \mathbf{w}(n) \\
e_p(n) &:= (d(n) - \mathbf{w}^H(n)\mathbf{u}(n)) - \xi_*(n) \\
&= (\tilde{\mathbf{w}}^H(n) - \mathbf{q}(n))^H \mathbf{u}(n) \\
e_a(n) &:= (d(n) - \mathbf{w}^H(n-1)\mathbf{u}(n)) - \xi_*(n) = \xi(n) - \xi_*(n) \\
&= \tilde{\mathbf{w}}^H(n-1)\mathbf{u}(n)
\end{aligned} \tag{2}$$

2 Energy Relation

In this section we will derive a fundamental deterministic energy relationship.

$$\begin{aligned}
\mathbf{w}(n) &= \mathbf{w}(n-1) + \mathbf{P}(n)\mathbf{u}(n)\xi^*(n) \\
\tilde{\mathbf{w}}(n) &= \tilde{\mathbf{w}}(n-1) - \mathbf{P}(n)\mathbf{u}(n)\xi^*(n) + \mathbf{q}(n)
\end{aligned} \tag{3}$$

$$\underbrace{(\tilde{\mathbf{w}}(n) - \mathbf{q}(n))^H \mathbf{u}(n)}_{e_p(n)} = \underbrace{\tilde{\mathbf{w}}^H(n-1)\mathbf{u}(n)}_{e_a(n)} - \underbrace{\mathbf{u}^H(n)\mathbf{P}(n)\mathbf{u}(n)}_{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2} \xi(n) \tag{4}$$

Note the use of the weighted Euclidean norm

$$\|\mathbf{a}\|_{\mathbf{B}}^2 := \mathbf{a}^H \mathbf{B} \mathbf{a}$$

where \mathbf{B} is a Hermitian positive-semi-definite matrix. Equation (4) implies that

$$\begin{aligned}
\xi(n) &= \|\mathbf{u}(n)\|_{\mathbf{P}(n)}^{-2} (e_a(n) - e_p(n)) \quad \text{when} \quad \mathbf{u}(n) \neq 0 \\
\tilde{\mathbf{w}}(n) - \mathbf{q}(n) &= \begin{cases} \tilde{\mathbf{w}}(n-1) - \|\mathbf{u}(n)\|_{\mathbf{P}(n)}^{-2} \mathbf{P}(n)\mathbf{u}(n)(e_a(n) - e_p(n))^* & \mathbf{u}(n) \neq 0 \\ \tilde{\mathbf{w}}(n-1) & \mathbf{u}(n) = 0 \end{cases} \\
&= \tilde{\mathbf{w}}(n-1) - \bar{\mu}(n)\mathbf{P}(n)\mathbf{u}(n)(e_a(n) - e_p(n))^*
\end{aligned} \tag{5}$$

where we use the psuedo-inverse to define

$$\bar{\mu}(n) := \left(\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 \right)^\dagger$$

Taking the $\mathbf{P}^{-1}(n)$ -weighted norm of both sides of (5), we get $\|\tilde{\mathbf{w}}(n) - \mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2$ for the left side and the following quantity for the right.

$$\begin{aligned}
&\left(\tilde{\mathbf{w}}^H(n-1) - \bar{\mu}(n)e_a(n)\mathbf{u}^H(n)\mathbf{P}(n) + \bar{\mu}(n)e_p(n)\mathbf{u}^H(n)\mathbf{P}(n) \right) \mathbf{P}^{-1}(n) \\
&\cdot \left(\tilde{\mathbf{w}}(n-1) - \bar{\mu}(n)e_a^*(n)\mathbf{P}(n)\mathbf{u}(n) + \bar{\mu}(n)e_p^*(n)\mathbf{P}(n)\mathbf{u}(n) \right) \\
&= \|\tilde{\mathbf{w}}(n-1)\|_{\mathbf{P}^{-1}(n)}^2 - \bar{\mu}(n)|e_a(n)|^2 + \bar{\mu}(n)e_p^*(n)e_a(n) \\
&\quad - \bar{\mu}(n)|e_a(n)|^2 + \bar{\mu}(n)|e_a(n)|^2 - \bar{\mu}(n)e_a(n)e_p^*(n) \\
&\quad + \bar{\mu}(n)e_p(n)e_a^*(n) - \bar{\mu}(n)e_p(n)e_a^*(n) + \bar{\mu}(n)|e_p(n)|^2 \\
&= \|\tilde{\mathbf{w}}(n-1)\|_{\mathbf{P}^{-1}(n)}^2 - \bar{\mu}(n)|e_a(n)|^2 + \bar{\mu}(n)|e_p(n)|^2
\end{aligned}$$

The energy relation is then summarized as

$$\|\tilde{\mathbf{w}}(n) - \mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2 + \bar{\mu}(n)|e_a(n)|^2 = \|\tilde{\mathbf{w}}(n-1)\|_{\mathbf{P}^{-1}(n)}^2 + \bar{\mu}(n)|e_p(n)|^2 \quad (6)$$

3 Random Walk Assumptions

We assume the following about the random-walk driving-noise $\{\mathbf{q}(n)\}$ in (1).

$$\begin{aligned} \text{A.1)} \quad & \mathbb{E}\{\mathbf{q}(n)\} = 0 \\ & \mathbb{E}\{\mathbf{q}(n)\mathbf{q}^H(n-k)\} = \mathbf{Q}\delta_k \quad \text{where } \delta_k \text{ denotes the Kronecker delta} \\ & \{\mathbf{q}(n)\} \perp\!\!\!\perp \{\mathbf{u}(n)\} \\ & \{\mathbf{q}(n)\} \perp\!\!\!\perp \{\boldsymbol{\xi}(n)\} \end{aligned}$$

Examining the expectation of the leftmost term of the energy relation (6), we have

$$\begin{aligned} & \mathbb{E}\{\|\tilde{\mathbf{w}}(n) - \mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2\} \\ & = \mathbb{E}\{\|\tilde{\mathbf{w}}(n)\|_{\mathbf{P}^{-1}(n)}^2\} - 2\Re \mathbb{E}\{\mathbf{q}^H(n)\mathbf{P}^{-1}(n)\tilde{\mathbf{w}}(n)\} + \mathbb{E}\{\|\mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2\} \end{aligned} \quad (7)$$

From (3) we have

$$\tilde{\mathbf{w}}(n) = \tilde{\mathbf{w}}(n-1) + \mathbf{q}(n) - \mathbf{P}(n)\mathbf{u}(n)\boldsymbol{\xi}^*(n)$$

allowing us to simplify the second term on the right side of (7):

$$\begin{aligned} & \mathbb{E}\{\mathbf{q}^H(n)\mathbf{P}^{-1}(n)\tilde{\mathbf{w}}(n)\} \\ & = \mathbb{E}\{\mathbf{q}^H(n)\mathbf{P}^{-1}(n)\tilde{\mathbf{w}}(n-1)\} + \mathbb{E}\{\|\mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2\} - \mathbb{E}\{\mathbf{q}^H(n)\mathbf{u}(n)\boldsymbol{\xi}^*(n)\} \\ & = \mathbb{E}\{\|\mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2\} \end{aligned}$$

where the first and third terms vanished as a result of A.1). Plugging the previous (real-valued) expression into (7) yields

$$\mathbb{E}\{\|\tilde{\mathbf{w}}(n) - \mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2\} = \mathbb{E}\{\|\tilde{\mathbf{w}}(n)\|_{\mathbf{P}^{-1}(n)}^2\} - \mathbb{E}\{\|\mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2\} \quad (8)$$

4 Steady-State Analysis

We claim that when the adaptation algorithm has reached “steady state”,

$$\mathbb{E}\{\|\tilde{\mathbf{w}}(n)\|_{\mathbf{P}^{-1}(n)}^2\} = \mathbb{E}\{\|\tilde{\mathbf{w}}(n-1)\|_{\mathbf{P}^{-1}(n)}^2\}$$

Taking the expectation of (6) and incorporating (8), we find the following steady state relationship:

$$\mathbb{E}\{\bar{\mu}(n)|e_a(n)|^2\} = \mathbb{E}\{\bar{\mu}(n)|e_p(n)|^2\} + \mathbb{E}\{\|\mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2\} \quad (9)$$

To proceed further, we make a few assumptions:

- A.2) $\mathbb{E}\{\mathbf{u}(n)\mathbf{u}^H(n)\} = \mathbf{R}$ and $\mathbf{R} > 0$
- A.3) $\begin{matrix} \{\xi_\star(n)\} \text{ i.i.d.} \\ \{\xi_\star(n)\} \perp\!\!\!\perp \{\mathbf{u}(n)\} \end{matrix} \Rightarrow \begin{matrix} \{\xi_\star(n)\} \perp\!\!\!\perp \{\tilde{\mathbf{w}}(n-1)\} \\ \{\xi_\star(n)\} \perp\!\!\!\perp \{e_a(n)\} \end{matrix}$
- A.4) $\mathbb{E}\{\mathbf{P}(n)\mathbf{u}(n)\mathbf{u}^H(n)\} = \mathbb{E}\{\mathbf{P}(n)\} \mathbb{E}\{\mathbf{u}(n)\mathbf{u}^H(n)\}$ (e.g., from $\lambda \approx 1$)
- A.5) $\mathbb{E}\{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 | e_a(n)|^2\} = \mathbb{E}\{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2\} \mathbb{E}\{|e_a(n)|^2\}$ (e.g., from large M)
- A.6) $\lim_{n \rightarrow \infty} \mathbb{E}\{\Phi^{-1}(n)\} = (\lim_{n \rightarrow \infty} \mathbb{E}\{\Phi(n)\})^{-1}$ (e.g., Wishart theory [3, p. 452])

First, using the implications of A.3), we have

$$\begin{aligned} J(n) &:= \mathbb{E}\{|\xi(n)|^2\} \\ &= \mathbb{E}\{|e_a(n) + \xi_\star(n)|^2\} \\ &= \mathbb{E}\{|e_a(n)|^2\} + \mathbb{E}\{|\xi_\star(n)|^2\} \\ &= \mathbb{E}\{|e_a(n)|^2\} + J_{\min} \\ J_{\text{emse}} &:= \lim_{n \rightarrow \infty} J(n) - J_{\min} \\ &= \lim_{n \rightarrow \infty} \mathbb{E}\{|e_a(n)|^2\} \end{aligned}$$

Then, from (2), (4), and A.3), we see that the first term on the right side of (9) can be written as

$$\begin{aligned} &\mathbb{E}\{\bar{\mu}(n)|e_p(n)|^2\} \\ &= \mathbb{E}\left\{\bar{\mu}(n) \left| e_a(n) - \|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 \xi(n) \right|^2\right\} \\ &= \mathbb{E}\left\{\bar{\mu}(n) \left| (1 - \|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2) e_a(n) + \|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 \xi_\star(n) \right|^2\right\} \\ &= \mathbb{E}\{\bar{\mu}(n)|e_a(n)|^2\} - 2 \mathbb{E}\{|e_a(n)|^2\} + \mathbb{E}\{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 | e_a(n)|^2\} + \mathbb{E}\{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 |\xi_\star(n)|^2\} \end{aligned}$$

So the steady-state relationship (9) becomes (after cancellation of $\mathbb{E}\{\bar{\mu}(n)|e_a(n)|^2\}$ terms)

$$2 \mathbb{E}\{|e_a(n)|^2\} = \mathbb{E}\{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 | e_a(n)|^2\} + \mathbb{E}\{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 |\xi_\star(n)|^2\} + \mathbb{E}\{\|\mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2\} \quad (10)$$

Looking at the first term on the right side of (10), we have, from A.4) and A.5),

$$\begin{aligned} \mathbb{E}\{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 | e_a(n)|^2\} &= \mathbb{E}\{\|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2\} \mathbb{E}\{|e_a(n)|^2\} \\ &= \text{tr}\left(\mathbb{E}\{\mathbf{P}(n)\mathbf{u}(n)\mathbf{u}^H(n)\}\right) \mathbb{E}\{|e_a(n)|^2\} \\ &= \text{tr}\left(\mathbb{E}\{\mathbf{P}(n)\} \mathbb{E}\{\mathbf{u}(n)\mathbf{u}^H(n)\}\right) \mathbb{E}\{|e_a(n)|^2\} \\ &= \text{tr}\left(\mathbb{E}\{\mathbf{P}(n)\} \mathbf{R}\right) \mathbb{E}\{|e_a(n)|^2\} \end{aligned}$$

where $\mathbb{E}\{\mathbf{P}(n)\}$ requires further investigation. Using the fact that

$$\begin{aligned}\mathbb{E}\{\Phi(n)\} &= \sum_{i=1}^n \lambda^{n-i} \mathbb{E}\{\mathbf{u}(n)\mathbf{u}^H(n)\} + \delta\lambda^n \mathbf{I} \\ &= \begin{cases} \frac{1-\lambda^n}{1-\lambda} \mathbf{R} + \delta\lambda^n \mathbf{I} & \lambda < 1 \\ n\mathbf{R} + \delta\mathbf{I} & \lambda = 1 \end{cases}\end{aligned}$$

we find, via A.6),

$$\begin{aligned}\lim_{n \rightarrow \infty} \mathbb{E}\{\mathbf{P}(n)\} &= \left(\lim_{n \rightarrow \infty} \mathbb{E}\{\Phi(n)\} \right)^{-1} \\ &= \begin{cases} (1-\lambda)\mathbf{R}^{-1} & \lambda < 1 \\ 0 & \lambda = 1 \end{cases}\end{aligned}$$

implying that

$$\lim_{n \rightarrow \infty} \mathbb{E}\left\{ \|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 |e_a(n)|^2 \right\} = \begin{cases} M(1-\lambda)J_{\text{emse}} & \lambda < 1 \\ 0 & \lambda = 1 \end{cases}$$

Looking next at the second term on the right side of (10), we get from A.3) and A.6)

$$\lim_{n \rightarrow \infty} \mathbb{E}\left\{ \|\mathbf{u}(n)\|_{\mathbf{P}(n)}^2 |\xi_*(n)|^2 \right\} = \begin{cases} M(1-\lambda)J_{\text{min}} & \lambda < 1 \\ 0 & \lambda = 1 \end{cases}$$

For the last term on the right side of (10), assumptions A.1) and A.2) yield

$$\begin{aligned}\mathbb{E}\left\{ \|\mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2 \right\} &= \mathbb{E}\left\{ \mathbf{q}^H(n)\Phi(n)\mathbf{q}(n) \right\} \\ &= \text{tr} \left(\mathbb{E}\left\{ \mathbf{q}(n)\mathbf{q}^H(n)\Phi(n) \right\} \right) \\ &= \text{tr} \left(\mathbb{E}\left\{ \mathbf{q}(n)\mathbf{q}^H(n) \right\} \sum_{i=1}^n \lambda^{n-i} \mathbb{E}\left\{ \mathbf{u}(n)\mathbf{u}^H(n) \right\} + \delta\lambda^n \mathbb{E}\left\{ \mathbf{q}(n)\mathbf{q}^H(n) \right\} \right) \\ &= \text{tr}(\mathbf{Q}\mathbf{R}) \sum_{i=1}^n \lambda^{n-i} + \delta\lambda^n \text{tr}(\mathbf{Q}) \\ &= \begin{cases} \frac{1-\lambda^n}{1-\lambda} \text{tr}(\mathbf{Q}\mathbf{R}) + \delta\lambda^n \text{tr}(\mathbf{Q}) & \lambda < 1 \\ n \text{tr}(\mathbf{Q}\mathbf{R}) + \delta \text{tr}(\mathbf{Q}) & \lambda = 1 \end{cases}\end{aligned}$$

so that

$$\lim_{n \rightarrow \infty} \mathbb{E}\left\{ \|\mathbf{q}(n)\|_{\mathbf{P}^{-1}(n)}^2 \right\} = \begin{cases} (1-\lambda)^{-1} \text{tr}(\mathbf{Q}\mathbf{R}) & \lambda < 1 \\ \infty & \lambda = 1 \text{ and } \mathbf{Q} \neq \mathbf{0} \\ 0 & \lambda = 1 \text{ and } \mathbf{Q} = \mathbf{0} \end{cases}$$

Collecting our findings on the asymptotic behavior of (10), we have

$$2J_{\text{emse}} = \begin{cases} M(1-\lambda)J_{\text{emse}} + M(1-\lambda)J_{\text{min}} + (1-\lambda)^{-1} \text{tr}(\mathbf{Q}\mathbf{R}) & \lambda < 1 \\ \infty & \lambda = 1 \text{ and } \mathbf{Q} \neq \mathbf{0} \\ 0 & \lambda = 1 \text{ and } \mathbf{Q} = \mathbf{0} \end{cases}$$

which, for the $\lambda < 1$ case, gives

$$J_{\text{emse, RLS}} = \frac{M(1-\lambda)J_{\min} + (1-\lambda)^{-1} \text{tr}(\mathbf{QR})}{2 - M(1-\lambda)} \quad (11)$$

$$\approx \frac{1}{2} \left(M(1-\lambda)J_{\min} + (1-\lambda)^{-1} \text{tr}(\mathbf{QR}) \right) \quad \text{when } |M(1-\lambda)| \ll 2 \quad (12)$$

Note the EMSE component due to J_{\min} and due to time variations (i.e., \mathbf{Q}).

5 Optimum Forgetting Factor

The value of λ that minimizes J_{emse} can be obtained by zeroing the partial derivative of (12) with respect to $(1-\lambda)$. This yields

$$\lambda_{\text{opt}} \approx 1 - \sqrt{\frac{\text{tr}(\mathbf{QR})}{MJ_{\min}}} \quad (13)$$

$$J_{\text{emse, RLS}}|_{\text{opt}} \approx \sqrt{MJ_{\min} \text{tr}(\mathbf{QR})} \quad (14)$$

6 Comparison to LMS

Recall the counterparts of (11)–(14) for LMS:

$$J_{\text{emse, LMS}} = \frac{\mu \text{tr}(\mathbf{R})J_{\min} + \mu^{-1} \text{tr}(\mathbf{Q})}{2 - \mu \text{tr}(\mathbf{R})} \quad (15)$$

$$\approx \frac{1}{2} \left(\mu \text{tr}(\mathbf{R})J_{\min} + \mu^{-1} \text{tr}(\mathbf{Q}) \right) \quad \text{when } \mu \text{tr}(\mathbf{R}) \ll 2 \quad (16)$$

$$\mu_{\text{opt}} \approx \sqrt{\frac{\text{tr}(\mathbf{Q})}{J_{\min} \text{tr}(\mathbf{R})}} \quad (17)$$

$$J_{\text{emse, LMS}}|_{\text{opt}} \approx \sqrt{J_{\min} \text{tr}(\mathbf{R}) \text{tr}(\mathbf{Q})} \quad (18)$$

Comparing the optimal values of EMSE for LMS and RLS we find

$$\frac{J_{\text{emse, LMS}}|_{\text{opt}}}{J_{\text{emse, RLS}}|_{\text{opt}}} = \sqrt{\frac{\text{tr}(\mathbf{R}) \text{tr}(\mathbf{Q})}{M \text{tr}(\mathbf{QR})}} \quad (19)$$

Thus the relationship between \mathbf{R} and \mathbf{Q} will determine which of the two algorithms gives lower steady-state MSE. A few instructive cases are presented below [3]. It is interesting to note that the simple LMS algorithm can have exhibit *tracking* performance superior to the computationally-intensive RLS algorithm in certain environments. However, it should be noted that the *convergence* of RLS is typically much faster than that of LMS.

- $\mathbf{Q} = \sigma_q^2 \mathbf{I}$: In this case we find that the two algorithms provide essentially the same level of steady-state MSE.

$$J_{\text{emse}} \approx \sqrt{M J_{\text{min}} \sigma_q^2 \text{tr}(\mathbf{R})}$$

- $\mathbf{Q} = c\mathbf{R}$: In this case LMS yields lower steady-state MSE:

$$\frac{J_{\text{emse, LMS}}|_{\text{opt}}}{J_{\text{emse, RLS}}|_{\text{opt}}} = \sqrt{\frac{\text{tr}(\mathbf{R})^2}{M \text{tr}(\mathbf{R}^2)}} < 1$$

- $\mathbf{Q} = c\mathbf{R}^{-1}$: In this case RLS yields lower steady-state MSE:

$$\frac{J_{\text{emse, LMS}}|_{\text{opt}}}{J_{\text{emse, RLS}}|_{\text{opt}}} = \frac{1}{M} \sqrt{\text{tr}(\mathbf{R}) \text{tr}(\mathbf{R}^{-1})} > 1$$

The inequalities above can be proven using the Cauchy-Schwarz inequality for vectors: $|\mathbf{x}^H \mathbf{y}|^2 \leq \|\mathbf{x}\|^2 \|\mathbf{y}\|^2$.

References

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