

## HOMEWORK SOLUTIONS #5

## 1. Poor 4.6

As each estimate relies on the knowledge of the conditional pdf  $w(\theta|y)$ , we'll determine this first.

$$\begin{aligned}\underline{Y} &= \frac{1}{\sqrt{\Theta}} \underline{N} \\ \underline{N} &\sim \mathcal{N}(\underline{0}, \Sigma) \quad \text{where } \Sigma = \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \\ \underline{Y}|\theta &\sim \mathcal{N}\left(\underline{0}, \frac{1}{\theta}\Sigma\right) \\ w(\theta|\underline{y}) &= \frac{p_\theta(\underline{y})w(\theta)}{p(\underline{y})} = \frac{\frac{1}{\alpha} \frac{1}{2\pi|\frac{1}{\theta}\Sigma|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2}\underline{y}^T \left(\frac{1}{\theta}\Sigma\right)^{-1} \underline{y}\right\} I_{[0,\alpha]}(\theta)}{\int_0^\alpha \frac{1}{\alpha} \frac{1}{2\pi|\frac{1}{\theta}\Sigma|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2}\underline{y}^T \left(\frac{1}{\theta}\Sigma\right)^{-1} \underline{y}\right\} d\theta}\end{aligned}$$

where  $I_{[0,\alpha]}(\theta)$  equals 1 for  $\theta \in [0, \alpha]$  and 0 otherwise.

$$\begin{aligned}\text{let } \tau &= \frac{1}{2}\underline{y}^T \Sigma^{-1} \underline{y} \\ \text{then } w(\theta|\underline{y}) &= \frac{\theta e^{-\tau\theta}}{\int_0^\alpha \theta e^{-\tau\theta} d\theta} \\ \text{since } \left(\frac{1}{\theta}\Sigma\right)^{-1} &= \theta\Sigma^{-1} \quad \text{and } \left|\frac{1}{\theta}\Sigma\right|^{\frac{1}{2}} = \frac{1}{\theta} |\Sigma|^{\frac{1}{2}}\end{aligned}$$

Using integration by parts,

$$\int_0^\alpha \theta e^{-\tau\theta} d\theta = \frac{1 - e^{-\alpha\tau}(\alpha\tau + 1)}{\tau^2}$$

(a) For the MMSE estimate, we find

$$\begin{aligned}\hat{\theta}_{\text{MMSE}}(y) &= \int_\Lambda \theta w(\theta|y) d\theta \\ &= \frac{\int_0^\alpha \theta^2 e^{-\tau\theta} d\theta}{\frac{1 - e^{-\alpha\tau}(\alpha\tau + 1)}{\tau^2}} \\ &= \frac{2 - e^{-\alpha\tau}(2\alpha\tau + 2 + \alpha^2\tau^2)}{\frac{1 - e^{-\alpha\tau}(\alpha\tau + 1)}{\tau^2}} \\ &= \frac{2 - e^{-\alpha\tau}(2 + 2\alpha\tau + \alpha^2\tau^2)}{\tau[1 - e^{-\alpha\tau}(\alpha\tau + 1)]}\end{aligned}$$

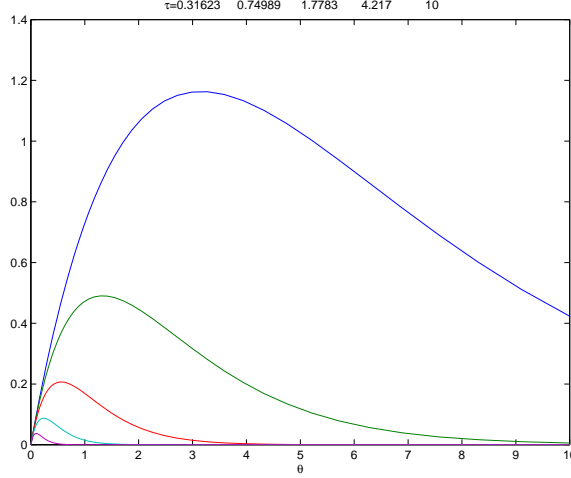
where the numerator was derived using integration by parts.

(b) For the MAP estimate,

$$\hat{\theta}_{\text{MAP}}(\underline{y}) = \arg \max_{\theta} w(\theta|\underline{y}) = \arg \max_{\theta} p_\theta(\underline{y})w(\theta) = \arg \max_{\theta \in [0,\alpha]} p_\theta(\underline{y}) = \arg \max_{\theta \in [0,\alpha]} \theta e^{-\tau\theta}$$

As  $\theta e^{-\tau\theta}$  is unimodal in  $\theta$  (see example plots below), the maximum of is attained at the zero-derivative point.

$$\frac{\partial}{\partial \theta} \theta e^{-\tau\theta} = e^{-\tau\theta} - \tau\theta e^{-\tau\theta} = 0 \Rightarrow \theta = \frac{1}{\tau}$$



Thus,

$$\hat{\theta}_{\text{MAP}}(\underline{y}) = \begin{cases} \alpha & \text{if } \frac{1}{\tau} > \alpha \\ \frac{1}{\tau} & \text{else} \end{cases}, \quad \tau = \frac{\underline{y}^T \Sigma^{-1} \underline{y}}{2}$$

(c) For the MMAE estimate, we leverage the continuity of  $w(\theta|y)$  to claim that

$$\hat{\theta}_{\text{MMAE}} = \hat{\theta} \text{ s.t. } \frac{1}{2} = \int_0^{\hat{\theta}} w(\theta|y) d\theta = \frac{1 - e^{-\hat{\theta}\tau}(\hat{\theta}\tau + 1)}{1 - e^{-\alpha\tau}(\alpha\tau + 1)}$$

## 2. Poor 4.8

Using the indicator function

$$I_A(x) = \begin{cases} 1 & x \in A \\ 0 & x \notin A \end{cases}$$

we have

$$\begin{aligned} p_N(\nu) &= e^{-\nu} I_{[0, \infty)}(\nu) \\ w(\theta) &= e^{-\theta} I_{[0, \infty)}(\theta) \end{aligned}$$

and since  $Y = N + \Theta$ ,

$$p(y|\theta) = e^{-(y-\theta)} I_{[\theta, \infty)}(y) = e^{-(y-\theta)} I_{(-\infty, y)}(\theta) = e^{-(y-\theta)} I_{(-\infty, y)}(\theta) I_{[\theta, \infty)}(y)$$

Then

$$\begin{aligned} p(y) &= \int p(y|\theta) w(\theta) d\theta = \int_0^{\infty} e^{-(y-\theta)} e^{-\theta} I_{(-\infty, y)}(\theta) d\theta \\ &= \int_0^{\max(0, y)} e^{-y} d\theta = y e^{-y} I_{[0, \infty)}(y) \end{aligned}$$

Note that  $Y, N, \Theta$  are positive. The posterior pdf has a uniform distribution on  $[0, y)$ :

$$w(\theta|y) = \frac{p(y|\theta)w(\theta)}{p(y)} = \frac{e^{-(y-\theta)} I_{(-\infty, y)}(\theta) e^{-\theta} I_{[0, \infty)}(\theta)}{y e^{-y} I_{[0, \infty)}(y)} = \begin{cases} \frac{1}{y} & 0 \leq \theta < y \\ 0 & \text{else} \end{cases}$$

(a) The uniform distribution implies

$$\hat{\theta}_{\text{MMSE}}(y) = \hat{\theta}_{\text{MMAE}}(y) = \text{E}\{\Theta|y\} = \frac{y}{2}$$

(b) The MMSE equals

$$\text{E}\{(\hat{\theta}(Y) - \Theta)^2\} = \text{E}\{\text{var}(\Theta)|Y\}$$

Because  $\Theta|Y \sim \mathcal{U}[0, Y)$ , we know  $\text{var}(\Theta)|Y = Y^2/12$ . Finally,

$$\text{MMSE} = \text{E}\{Y^2/12\} = \frac{1}{12} \int_0^\infty y^3 e^{-y} dy = \frac{1}{2}$$

(c) In this case

$$\begin{aligned} p(\underline{y}|\theta) &= \prod_{k=1}^n e^{-(y_k-\theta)} I_{[0,\infty)}(y_k) = \prod_{k=1}^n e^{-(y_k-\theta)} I_{(-\infty, y_k)}(\theta) \\ &= I_{(-\infty, \min\{y_k\})}(\theta) e^{n\theta} \prod_{k=1}^n e^{-y_k} \end{aligned}$$

so that

$$p(\underline{y}|\theta)w(\theta) = I_{[0, \min\{y_k\})}(\theta) e^{(n-1)\theta} \prod_{k=1}^n e^{-y_k}$$

Then

$$\begin{aligned} \hat{\theta}_{\text{MAP}}(\underline{y}) &= \arg \max_{\theta} w(\theta|y) = \arg \max_{\theta} p(\underline{y}|\theta)w(\theta) \\ &= \arg \max_{\theta} I_{[0, \min\{y_k\})}(\theta) e^{(n-1)\theta} \\ &= \begin{cases} \{\theta \in [0, \min_k\{y_k\})\} & n = 1 \\ \min_k\{y_k\} & n > 1 \end{cases} \end{aligned}$$

Note that, in the case  $n = 1$ ,  $\hat{\theta}_{\text{MAP}}(\underline{y})$  is not uniquely specified.

3. **Poor 4.11** We can formulate this problem as

$$\underline{Y} = \Theta \underline{s} + \underline{N}$$

for

$$\begin{aligned} \underline{s} &= [\alpha, \alpha^2, \dots, \alpha^n]^t \\ \underline{N} &\sim \mathcal{N}(\underline{0}, \sigma^2 I) \\ \Theta &\sim \mathcal{N}(0, q^2) \end{aligned}$$

This is a specific case of the model used in Example IV.B.2, “Estimation of Signal Amplitude.”

(a) From the example, we recall that  $\Theta|y \sim \mathcal{N}(m, v^2)$ , where

$$\begin{aligned} m &= \frac{\sigma^{-2} \underline{s}^t \underline{y}}{\sigma^{-2} \underline{s}^t \underline{s} + q^{-2}} = \frac{\sum_{i=1}^n \alpha^i y_i}{(\sigma/q)^2 + \sum_{i=1}^n \alpha^{2i}} \\ v^2 &= \frac{1}{\sigma^{-2} \underline{s}^t \underline{s} + q^{-2}} = \frac{\sigma^2}{(\sigma/q)^2 + \sum_{i=1}^n \alpha^{2i}} \end{aligned}$$

and the conditional mean implies  $\hat{\theta}_{\text{MMSE}}(\underline{y}) = m$ .

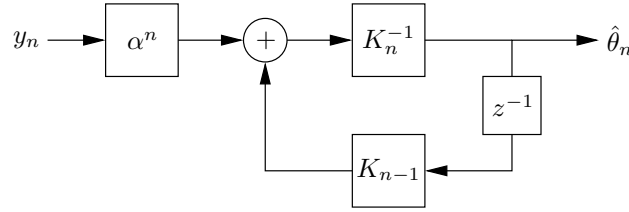
- (b) The denominator of  $m$  and  $v^2$  can be written as  $K_n = K_{n-1} + \alpha^{2n}$ , for  $n = 1, 2, \dots$ , when  $K_0 = (\sigma/q)^2$ . Then we can see that

$$K_n \hat{\theta}_n(\underline{y}) = \sum_{i=1}^n \alpha^i y_i = \alpha^n y_n + \sum_{i=1}^{n-1} \alpha^i y_i = \alpha^n y_n + K_{n-1} \hat{\theta}_{n-1}(\underline{y})$$

where  $\hat{\theta}_n$  denotes the  $n$ -sample MMSE estimator. Dividing by  $K_n$  yields the recursive formula

$$\hat{\theta}_n(\underline{y}) = K_n^{-1}(\alpha^n y_n + K_{n-1} \hat{\theta}_{n-1}(\underline{y}))$$

The block diagram is illustrated below.



- (c) For the  $n$ -sample MMSE estimator, we know that the MMSE is given by the  $n$ -sample conditional variance:

$$e_n = E\{(\hat{\theta}_n - \Theta)^2\} = E\{\text{var}(\Theta|\underline{y})\} = E\{v^2\} = v^2 = \frac{\sigma^2}{(\sigma/q)^2 + \sum_{i=1}^n \alpha^{2i}}$$

Since  $\lim_{n \rightarrow \infty} \sum_{i=1}^n \alpha^{2i} = \frac{1}{1-\alpha^2} - 1 = \frac{\alpha^2}{1-\alpha^2}$  when  $|\alpha| < 1$ ,

$$\lim_{n \rightarrow \infty} e_n = \frac{\sigma^2}{(\sigma/q)^2 + \frac{\alpha^2}{1-\alpha^2}}$$

For finite  $n$ , we also note that the following cases yield perfect estimation:

$$\lim_{\sigma \rightarrow \infty} e_n = 0, \quad \lim_{q \rightarrow 0} e_n = 0,$$