

**Non-coherent Detection of an AM Signal  
in Additive White Gaussian Noise:**

$$H_0 : \underline{Y} = \underline{N}$$

$$H_1 : \underline{Y} = \underline{N} + \underline{s}(\theta)$$

Problem definition:

- $\underline{N} \sim \mathcal{N}(\underline{0}, \sigma^2 I)$
- $s_k(\theta) = a_k \sin((k-1)\omega_c T_s + \theta) \quad k = 1, \dots, n$
- $a_1, \dots, a_n$  known sequence of amplitudes ("pulse shape")
- $\omega_c$  known carrier frequency
- $T_s$  known sampling period  
(assume  $n\omega_c T_s = 2\pi m$ , i.e., integer # of periods in signal)
- $\Theta \sim U[0, 2\pi]$  random phase

1

Likelihood ratio:

$$\begin{aligned} L(\underline{y}) &= \frac{p_1(\underline{y})}{p_0(\underline{y})} = \frac{\frac{1}{2\pi} \int_0^{2\pi} p_{1,\theta}(\underline{y}) d\theta}{p_0(\underline{y})} \\ &= \frac{1}{2\pi} \int_0^{2\pi} \left[ \frac{p_{1,\theta}(\underline{y})}{p_0(\underline{y})} \right] d\theta \\ &= \frac{1}{2\pi} \int_0^{2\pi} \exp \left\{ \underline{s}(\theta)^T \Sigma^{-1} \left( \underline{y} - \frac{1}{2} \underline{s}(\theta) \right) \right\} d\theta \\ &= \frac{1}{2\pi} \int_0^{2\pi} \exp \left\{ \frac{1}{\sigma^2} \sum_{k=1}^n y_k s_k(\theta) - \frac{1}{2\sigma^2} \sum_{k=1}^n s_k^2(\theta) \right\} d\theta \end{aligned}$$

since  $\Sigma = \sigma^2 I$ .

2

Want to isolate  $\theta$ .

Recall  $s_k(\theta) = a_k \sin((k-1)\omega_c T_s + \theta)$ .

- using  $\sin(a+b) = \cos a \sin b + \sin a \cos b$   
first term:

$$\sum_{k=1}^n y_k s_k(\theta) = y_c \sin \theta + y_s \cos \theta$$

$$y_c := \sum_{k=1}^n y_k a_k \cos((k-1)\omega_c T_s)$$

$$y_s := \sum_{k=1}^n y_k a_k \sin((k-1)\omega_c T_s)$$

- using  $\sin^2 a = \frac{1}{2} - \frac{1}{2} \cos 2a$   
second term:

$$-\frac{1}{2} \sum_{k=1}^n s_k^2(\theta) = -\frac{1}{4} \sum_{k=1}^n a_k^2 + \frac{1}{4} \underbrace{\sum_{k=1}^n a_k^2 \cos(2(k-1)\omega_c T_s + 2\theta)}_{= 0 \text{ (filtered double freq term)}}$$

$$= -\frac{na^2}{4}$$

$$\text{where } \bar{a}^2 := \frac{1}{n} \sum_{k=1}^n a_k^2$$

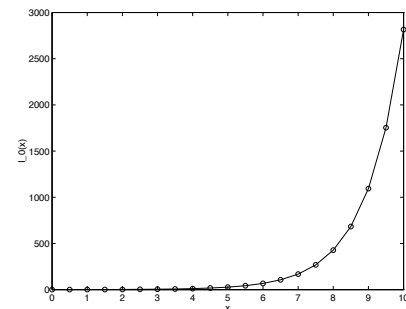
3

$$\begin{aligned} \text{Thus } L(\underline{y}) &= \exp \left\{ -\frac{na^2}{4\sigma^2} \right\} \\ &\quad \times \frac{1}{2\pi} \int_0^{2\pi} \exp \left\{ \frac{1}{\sigma^2} (y_c \sin \theta + y_s \cos \theta) \right\} d\theta \\ &= \exp \left\{ -\frac{na^2}{4\sigma^2} \right\} I_0 \left( \frac{r}{\sigma^2} \right) \end{aligned}$$

$$\text{where } r := \sqrt{y_c^2 + y_s^2}$$

$$\text{and } I_0(u) := \frac{1}{2\pi} \int_0^{2\pi} \exp\{u \cos(\theta - \phi)\} d\theta \quad \forall \phi$$

= modified Bessel function (see Poor p.34)

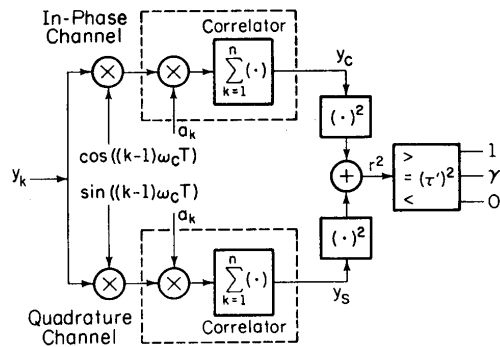


Since monotonic increasing in  $r$ , the LRT takes the form:

$$r^2 = (y_c^2 + y_s^2) \underset{<}{>} (\tau^A)^2$$

4

### Envelope Detector:



5

### Detector Performance:

Need to examine the statistics of

$$(Y_c^2 + Y_s^2)$$

Recalling definitions of  $y_c$  and  $y_s$ :

$$Y_c := \sum_{k=1}^n Y_k a_k \cos((k-1)\omega_c T_s)$$

$$Y_s := \sum_{k=1}^n Y_k a_k \sin((k-1)\omega_c T_s)$$

$Y_k$  Gaussian  $\Rightarrow Y_c$  and  $Y_s$  Gaussian, but statistics depend on whether  $H_0$  or  $H_1$  is true.

For now, condition on  $H_0$  (where  $Y_k = N_k$ ).

$$\mathbf{E}\{Y_c|H_0\} = \sum_{k=1}^n \mathbf{E}\{Y_k|H_0\} a_k \cos((k-1)\omega_c T_s) = 0$$

$$\mathbf{E}\{Y_s|H_0\} = \sum_{k=1}^n \underbrace{\mathbf{E}\{Y_k|H_0\}}_{=0} a_k \sin((k-1)\omega_c T_s) = 0$$

6

Now the variance under  $H_0$ :

$$\begin{aligned} \text{Var}\{Y_c|H_0\} &= \mathbf{E}\{Y_c^2|H_0\} \\ &= \sum_{k=1}^n \sum_{l=1}^n a_k a_l \mathbf{E}\{N_k N_l\} \times \\ &\quad \cos((k-1)\omega_c T_s) \cos((l-1)\omega_c T_s) \\ &= \sigma^2 \sum_{k=1}^n a_k^2 \cos^2((k-1)\omega_c T_s) \\ &= \frac{\sigma^2}{2} \sum_{k=1}^n a_k^2 + \underbrace{\frac{\sigma^2}{2} \sum_{k=1}^n a_k^2 \cos(2(k-1)\omega_c T_s)}_{=0 \text{ (filtered double freq term)}} \\ &= \frac{\sigma^2 n \bar{a}^2}{2} \end{aligned}$$

and using similar arguments

$$\text{Var}\{Y_s|H_0\} = \frac{\sigma^2 n \bar{a}^2}{2}$$

So, both  $Y_c$  and  $Y_s$  distributed as

$$Y_c, Y_s | H_0 \sim \mathcal{N}\left(0, \frac{\sigma^2 n \bar{a}^2}{2}\right)$$

What else is needed to characterize the Gaussian vector  $[Y_c, Y_s]^T$ ?

7

Covariance:

$$\begin{aligned} \text{Cov}\{Y_c, Y_s|H_0\} &= \mathbf{E}\{Y_c Y_s|H_0\} \\ &= \sum_{k=1}^n \sum_{l=1}^n a_k a_l \mathbf{E}\{N_k N_l\} \times \\ &\quad \cos((k-1)\omega_c T_s) \sin((l-1)\omega_c T_s) \\ &= \sigma^2 \sum_{k=1}^n a_k^2 \cos((k-1)\omega_c T_s) \sin((k-1)\omega_c T_s) \\ &= \frac{\sigma^2}{2} \sum_{k=1}^n a_k^2 \sin(2(k-1)\omega_c T_s) \\ &= 0. \end{aligned}$$

using  $\sin(2b) = 2 \sin(b) \cos(b)$ , and assuming that double frequency term is filtered by pulse shape  $\{a_k^2\}$ .

8

### Probability of False Alarm:

Know that, under  $H_0$ , have  $Y_c, Y_s$  i.i.d.  $\sim \mathcal{N}(0, n\sigma^2 a^2/2)$ .

Since LRT compares  $y_c^2 + y_s^2$  to  $(\tau')^2$ , no randomization needed.

$$P_0[\Gamma_1] = \iint_{\{y_c^2 + y_s^2 \geq (\tau')^2\}} \frac{1}{\pi n \sigma^2 a^2} \exp\left\{-\frac{y_c^2 + y_s^2}{n \sigma^2 a^2}\right\} dy_c dy_s$$

converting to polar coordinates:

$$r = \sqrt{y_c^2 + y_s^2} \quad \psi = \arctan\left(\frac{y_s}{y_c}\right)$$

plug in

$$\begin{aligned} P_0[\Gamma_1] &= \frac{1}{\pi n \sigma^2 a^2} \int_0^{2\pi} \int_{\tau'}^{\infty} r \exp\left\{-\frac{r^2}{n \sigma^2 a^2}\right\} dr d\psi \\ &= \frac{1}{\pi n \sigma^2 a^2} \left(\int_0^{2\pi} d\psi\right) \left(\int_{\tau'}^{\infty} r \exp\left\{-\frac{r^2}{n \sigma^2 a^2}\right\} dr\right) \\ &= \exp\left\{-\frac{(\tau')^2}{n \sigma^2 a^2}\right\} \end{aligned}$$

9

### Probability of Detection:

Now need statistics of  $Y_s$  and  $Y_c$  under  $H_1$ .

Strategy: Condition on  $\Theta = \theta$ , then integrate out later.

$$\mathbf{E}\{Y_k | H_1, \Theta = \theta\} = a_k \sin((k-1)\omega_c T_s + \theta)$$

Use this, trig identities, and cancellation of double freq terms, get

$$\begin{bmatrix} Y_c \\ Y_s \end{bmatrix} \Big|_{H_1, \theta} \sim \mathcal{N}\left(\begin{bmatrix} \frac{na^2}{2} \sin \theta \\ \frac{na^2}{2} \cos \theta \end{bmatrix}, \begin{bmatrix} \frac{na^2 \sigma^2}{2} & 0 \\ 0 & \frac{na^2 \sigma^2}{2} \end{bmatrix}\right)$$

$p_{Y_c, Y_s}(y_c, y_s | H_1)$

$$\begin{aligned} &= \int p_{Y_c, Y_s}(y_c, y_s | H_1, \theta) w(\theta) d\theta \\ &= \frac{1}{2\pi} \int_0^{2\pi} p_{Y_c, Y_s}(y_c, y_s | H_1, \theta) d\theta \\ &= \frac{1}{2\pi} \int_0^{2\pi} \frac{1}{\pi n a^2 \sigma^2} e^{-\frac{1}{n \sigma^2 a^2} \left[ (y_c - \frac{na^2}{2} \sin \theta)^2 + (y_s - \frac{na^2}{2} \cos \theta)^2 \right]} d\theta \\ &= \frac{1}{2\pi} \int_0^{2\pi} \frac{1}{\pi n a^2 \sigma^2} e^{-\frac{1}{n \sigma^2 a^2} \left[ y_c^2 + y_s^2 - na^2 y_c \sin \theta - na^2 y_s \cos \theta + \left(\frac{na^2}{2}\right)^2 \right]} d\theta \\ &= p_{Y_c, Y_s}(y_c, y_s | H_0) \cdot \frac{1}{2\pi} \int_0^{2\pi} e^{\frac{1}{\sigma^2} \left[ y_c \sin \theta + y_s \cos \theta - \frac{na^2}{4} \right]} d\theta \\ &= p_{Y_c, Y_s}(y_c, y_s | H_0) e^{-\frac{na^2}{4\sigma^2}} I_0\left(\frac{\sqrt{y_c^2 + y_s^2}}{\sigma^2}\right) \\ &\text{using } I_0\left(\frac{\sqrt{y_c^2 + y_s^2}}{\sigma^2}\right) = \frac{1}{2\pi} \int_0^{2\pi} e^{\frac{1}{\sigma^2} [y_c \sin \theta + y_s \cos \theta]} d\theta \end{aligned}$$

10

Thus

$$\begin{aligned} P_D &= \iint_{y_c^2 + y_s^2 \geq (\tau')^2} p_{Y_c, Y_s}(y_c, y_s | H_1) dy_c dy_s \\ &= \iint_{y_c^2 + y_s^2 \geq (\tau')^2} p_{Y_c, Y_s}(y_c, y_s | H_0) e^{-\frac{na^2}{4\sigma^2}} I_0\left(\frac{\sqrt{y_c^2 + y_s^2}}{\sigma^2}\right) dy_c dy_s \end{aligned}$$

Transforming to polar coordinates we get

$$\begin{aligned} P_D &= \int_{\tau_0}^{\infty} x \exp\left\{-\frac{x^2 + b^2}{2}\right\} I_0(bx) dx \\ &= Q(b, \tau_0) = \text{Marcum's Q function} \end{aligned}$$

with

$$\begin{aligned} b^2 &= \frac{na^2}{2\sigma^2} \quad \text{SNR parameter} \\ \tau_0 &= \frac{\tau'}{\sigma^2 b} \quad \text{normalized threshold} \\ x &= \frac{r}{\sigma^2 b} \quad \text{change of variable} \end{aligned}$$

For the ROC,

$$\begin{aligned} \alpha = P_F &= \exp\left\{-\frac{\tau_0^2}{2}\right\} \Rightarrow \tau_0 = \left[2 \log\left(\frac{1}{\alpha}\right)\right]^{\frac{1}{2}} \\ &\Rightarrow P_D = Q\left(b, \left[2 \log\left(\frac{1}{\alpha}\right)\right]^{\frac{1}{2}}\right) \end{aligned}$$

11

### Non-coherent vs. Coherent:

In coherent case, the key performance quantity was

$$\begin{aligned} d^2 &= \underline{\mathbf{s}}^T \Sigma^{-1} \underline{\mathbf{s}} \\ &= \frac{1}{\sigma^2} \sum_{k=1}^n a_k^2 \sin^2((k-1)\omega_c T_s + \theta) \\ &= \frac{na^2}{2\sigma^2} = b^2 \quad (\text{from previous slide}) \end{aligned}$$

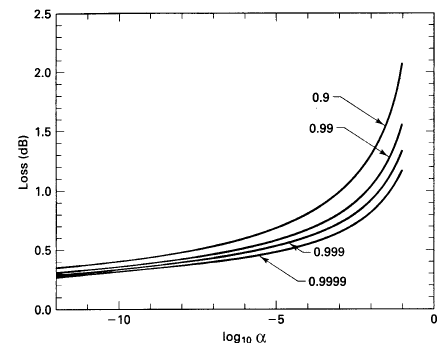
but the  $P_D$  expression was

$$P_D = 1 - \Phi(\Phi^{-1}(1 - \alpha) - d)$$

What are the values for  $b$  and  $d$  for equivalent performance?

$\rightsquigarrow$  for typical  $\alpha$  and SNR, need  $b \approx d + 0.4$ .

$\rightsquigarrow$  noncoherent needs a slightly higher SNR for equal performance.



12

What if  $s_0 \neq 0$ ?

$$\begin{aligned} L(\underline{y}) &= \frac{\mathbf{E}_1\{p_N(\underline{y} - \underline{s}_1(\Theta))\}}{\mathbf{E}_0\{p_N(\underline{y} - \underline{s}_0(\Theta))\}} \\ &= \frac{\mathbf{E}_1\{p_N(\underline{y} - \underline{s}_1(\Theta))/p_N(\underline{y})\}}{\mathbf{E}_0\{p_N(\underline{y} - \underline{s}_0(\Theta))/p_N(\underline{y})\}} \\ &= \frac{L_1(\underline{y})}{L_0(\underline{y})} \\ &= \frac{e^{-\frac{na^2}{4\sigma^2}} I_0\left(\frac{r_1}{\sigma^2}\right)}{e^{-\frac{na_0^2}{4\sigma^2}} I_0\left(\frac{r_0}{\sigma^2}\right)} \end{aligned}$$

use  $p_N(\underline{y})$  as a "catalyst"

Bayesian detection in "balanced" case:

- \* equal priors
- \* uniform costs
- \*  $a_1^2 = a_0^2$

$$\text{Bayes: } \delta(\underline{y}) = \begin{cases} 1 & r_1 \geq r_0 \\ 0 & < \end{cases}$$

further, if  $a_1^2 a_0 = 0$ ,

$$r(\delta) = P_e = \frac{1}{2} e^{-\frac{b^2}{4}}$$