ECE-700

Practice Midterm Solutions

PRACTICE MIDTERM SOLUTIONS

1. There are two approaches to this problem. First, we have the frequency-domain approach:

$$\begin{split} W(z) &= \frac{1}{D} \sum_{p=0}^{D-1} X(e^{\pm j\frac{2\pi}{D}p} z^{\frac{1}{D}}) \\ V(z) &= z^{-L} W(z) = z^{-L} \frac{1}{D} \sum_{p=0}^{D-1} X(e^{\pm j\frac{2\pi}{D}p} z^{\frac{1}{D}}) \\ Y(z) &= V(z^{U}) = z^{-LU} \frac{1}{D} \sum_{p=0}^{D-1} X(e^{\pm j\frac{2\pi}{D}p} z^{\frac{U}{D}}) \\ Y(e^{j\omega}) &= e^{-j\omega LU} \frac{1}{D} \sum_{p=0}^{D-1} X(e^{\pm j\frac{2\pi}{D}p} e^{j\omega \frac{U}{D}}) \\ &= e^{-j\omega LU} \frac{1}{D} \sum_{p=0}^{D-1} X(e^{j\frac{\omega U \pm 2\pi p}{D}}). \end{split}$$

Next, we have the time-domain approach:

$$\begin{split} w[l] &= x[lD] \\ v[l] &= w[l-L] = x[lD-LD] \\ y[m] &= \begin{cases} v[m/U] & \text{if } m \text{ is a multiple of } U \\ 0 & \text{else} \end{cases} \\ &= \begin{cases} x[m\frac{D}{U}-LD] & \text{if } m \text{ is a multiple of } U \\ 0 & \text{else} \end{cases} \\ Y(e^{j\omega}) &= \sum_{m = \text{ multiples of } U} x[m\frac{D}{U}-LD]e^{-j\omega m} \\ &= \sum_{l} x[lD-LD]e^{-j\omega lU} \\ &= \sum_{l} x[lD-LD]e^{-j\omega lU} \\ &= \sum_{n} \underbrace{\left(\frac{1}{D}\sum_{p=0}^{D-1}e^{\pm j\frac{2\pi}{D}pn}\right)}_{p=1 \text{ when } n \text{ is a multiple of } D, \text{ else } = 0 \end{cases} x[n]e^{-j\omega(\frac{n}{D}+L)U}, \end{split}$$

where we used the substitution n = lD - LD, i.e., $l = \frac{n}{D} + L$. Continuing,

$$Y(e^{j\omega}) = e^{-j\omega LU} \frac{1}{D} \sum_{p=0}^{D-1} \sum_{n} x[n] e^{-j\omega n \frac{U}{D}} e^{\pm j \frac{2\pi}{D} pn}$$

= $e^{-j\omega LU} \frac{1}{D} \sum_{p=0}^{D-1} X(e^{j \frac{\omega U \pm 2\pi p}{D}}).$

2. The design of each filter is based on the desired-signal-bandwidth at the input to that stage and the decimation factor of that stage. Recall that the desired-signal-bandwidth in $Y(e^{j\omega})$ is ω_o radians, and that the total decimation factor is $2 \times 2 \times 3 = 12$. Without loss of generality, we consider only positive frequencies below.



The signal $\{x[n]\}$ will be decimated by 12 to generate the output $\{y[n]\}$. Hence, the desired-signalbandwidth of $X(e^{j\omega})$ is $\frac{\omega_o}{12}$, and the passband edge of $H_0(z)$ should be $\frac{\omega_o}{12}$. Since the first stage decimates by 2, we can choose the transition band to extend symmetrically around $\frac{\pi}{2}$ in order to prevent aliasing into the desired-signal region. Hence, the stopband edge should start at $\pi - \frac{\omega_o}{12}$. (See figure below, which is unfortunately not drawn to scale!).



The signal $\{x_1[p]\}$ will be decimated by 6 to generate the output $\{y[n]\}$. Hence, the desired-signalbandwidth of $X_1(e^{j\omega})$ is $\frac{\omega_o}{6}$, and the passband edge of $H_1(z)$ should be $\frac{\omega_o}{6}$. Since the second stage decimates by 2, we can choose the transition band to extend symmetrically around $\frac{\pi}{2}$ in order to prevent aliasing into the desired-signal region. Hence, the stopband edge should start at $\pi - \frac{\omega_o}{6}$. (See figure below, which is unfortunately not drawn to scale!).



The signal $\{x_2[q]\}\$ will be decimated by 3 to generate the output $\{y[n]\}\$. Hence, the desired-signalbandwidth of $X_2(e^{j\omega})$ is $\frac{\omega_o}{3}$, and the passband edge of $H_2(z)$ should be $\frac{\omega_o}{3}$. Since the last stage decimates by 3, we can choose the first transition band to extend symmetrically around $\frac{\pi}{3}$ in order to prevent aliasing into the desired-signal region. Hence, the first stopband edge should start at $\frac{2\pi}{3} - \frac{\omega_o}{6}$. But, after decimation, the region $\left[\frac{2\pi}{3} + \frac{\omega_o}{3}, \pi\right)$ will also avoid the desired-signal region, and so we can apply a stopband edge at $\frac{2\pi}{3} + \frac{\omega_o}{3}$. (See figure below.).



To summarize:

	passband edge	stopband $edge(s)$
$H_0(z)$	$\omega_o/12$	$\pi - \frac{\omega_o}{12}$
$H_1(z)$	$\omega_o/6$	$\pi - rac{\omega_o}{6}$
$H_2(z)$	$\omega_o/3$	$\frac{2\pi}{3} - \frac{\omega_o}{3}, \frac{2\pi}{3} + \frac{\omega_o}{3}$

3. (a) If we define $\tilde{x}_c(t) := x_c(t + T + \Delta)$, then it is clear that

$$\begin{split} \tilde{X}_c(\Omega) &= \int_{-\infty}^{\infty} \tilde{x}_c(t) e^{-j\Omega t} dt \\ &= \int_{-\infty}^{\infty} x_c(t+T+\Delta) e^{-j\Omega t} dt \\ &= \int_{-\infty}^{\infty} x_c(\tau) e^{-j\Omega(\tau-T-\Delta)} dt \\ &= e^{j\Omega(T+\Delta)} X_c(\Omega) \end{split}$$

The top sampler generates $x_0[m]$, which is a sampling of $x_c(t)$ at rate $\frac{1}{2T}$, and the bottom sampler generates $x_1[m]$, which is a sampling of $\tilde{x}_c(t)$ at rate $\frac{1}{2T}$. Then

$$\begin{aligned} X_0(e^{j\omega}) &= \frac{1}{2T} \sum_k X_c \left(\frac{\omega - 2\pi k}{2T}\right) \\ X_1(e^{j\omega}) &= \frac{1}{2T} \sum_k \tilde{X}_c \left(\frac{\omega - 2\pi k}{2T}\right) \\ &= \frac{1}{2T} \sum_k X_c \left(\frac{\omega - 2\pi k}{2T}\right) e^{j(\frac{\omega - 2\pi k}{2T})(T + \Delta)} \end{aligned}$$

Upsampling yields

$$\begin{split} Y_0(e^{j\omega}) &= X_0(e^{j2\omega}) \\ &= \frac{1}{2T} \sum_k X_c \Big(\frac{2\omega - 2\pi k}{2T} \Big) \\ &= \frac{1}{2T} \sum_k X_c \Big(\frac{\omega - \pi k}{T} \Big) \\ Y_1(e^{j\omega}) &= e^{-j\omega} X_1(e^{j2\omega}) \\ &= e^{-j\omega} \frac{1}{2T} \sum_k X_c \Big(\frac{2\omega - 2\pi k}{2T} \Big) e^{j(\frac{2\omega - 2\pi k}{2T})(T + \Delta)} \\ &= \frac{1}{2T} \sum_k X_c \Big(\frac{\omega - \pi k}{T} \Big) e^{j(\omega - \pi k)(1 + \frac{\Delta}{T}) - j\omega} \\ &= \frac{1}{2T} \sum_k X_c \Big(\frac{\omega - \pi k}{T} \Big) e^{j(\omega - \pi k)\frac{\Delta}{T}} (-1)^k \\ Y(e^{j\omega}) &= Y_0(e^{j\omega}) + Y_1(e^{j\omega}) \\ &= \frac{1}{2T} \sum_k X_c \Big(\frac{\omega - \pi k}{T} \Big) \Big(1 + e^{j(\omega - \pi k)\frac{\Delta}{T}} (-1)^k \Big) \end{split}$$

(b) When $\Delta = 0$, the previous expression reduces to

$$Y(e^{j\omega}) = \frac{1}{2T} \sum_{k} X_c \left(\frac{\omega - \pi k}{T}\right) \left(1 + (-1)^k\right)$$
$$= \frac{1}{T} \sum_{k \text{ even}} X_c \left(\frac{\omega - \pi k}{T}\right)$$
$$= \frac{1}{T} \sum_{l} X_c \left(\frac{\omega - 2\pi l}{T}\right)$$

which is the DTFT that corresponds to sampling $x_c(t)$ at rate $\frac{1}{T}$, i.e., $y[n] = x_c(nT)$.

P. Schniter, 2006

(c) The block diagram can be simplified if we realize that the cascade of upsampling and downsampling with a one-sample delay/advance in the middle yields zero.



$$\xrightarrow{\text{since}} 2 \xrightarrow{z^{-1}} 2 \xrightarrow{$$

(d) Now we consider the simplified block diagram with F(z) = 1 and G(z) such that

$$G(e^{j\omega}) = e^{-j\omega\frac{\Delta}{2T}}$$
 for $\omega \in [-\pi, \pi)$.

Then, for $\omega \in [-\pi, \pi)$:

$$V_1(e^{j\omega}) = X_1(e^{j\omega})G(e^{j\omega})$$

= $\frac{1}{2T}\sum_k X_c \left(\frac{\omega - 2\pi k}{2T}\right) e^{j(\frac{\omega - 2\pi k}{2T})(T+\Delta)} e^{-j\omega\frac{\Delta}{2T}}$ for $\omega \in [-\pi, \pi)$

If this signal is upsampled by two and delayed by one sample, we get, for $\omega \in [-\pi, \pi)$:

$$\begin{aligned} \frac{1}{2T} \sum_{k} X_{c} \Big(\frac{2\omega - 2\pi k}{2T} \Big) e^{j(\frac{2\omega - 2\pi k}{2T})(T+\Delta)} e^{-j\omega \frac{\Delta}{T}} e^{-j\omega} \\ &= \frac{1}{2T} \sum_{k} X_{c} \Big(\frac{\omega - \pi k}{T} \Big) e^{j(\omega - \pi k)(1+\frac{\Delta}{T})} e^{-j\omega(1+\frac{\Delta}{T})} \\ &= \frac{1}{2T} \sum_{k} X_{c} \Big(\frac{\omega - \pi k}{T} \Big) e^{-j\pi k(1+\frac{\Delta}{T})} \end{aligned}$$

Since F(z) = 1, we have $V_0(e^{j\omega}) = X_0(e^{j\omega})$. Upsampling this by two gives

$$\frac{1}{2T} \sum_{k} X_c \left(\frac{\omega - \pi k}{T}\right)$$

Adding the last two signals to form w[m], we get

$$W(e^{j\omega}) = \frac{1}{2T} \sum_{k} X_c \left(\frac{\omega - \pi k}{T}\right) + \frac{1}{2T} \sum_{k} X_c \left(\frac{\omega - \pi k}{T}\right) e^{-j\pi k(1 + \frac{\Delta}{T})}$$
$$= \frac{1}{2T} \sum_{k} X_c \left(\frac{\omega - \pi k}{T}\right) \left(1 + (-1)^k e^{-j\frac{\pi\Delta k}{T}}\right)$$
$$\neq \frac{1}{2T} \sum_{k} X_c \left(\frac{\omega - \pi k}{T}\right) \left(1 + (-1)^k\right)$$
$$= \frac{1}{T} \sum_{l} X_c \left(\frac{\omega - 2\pi l}{T}\right)$$

(unless Δ is a multiple of 2T) and so

$$w[n] \neq w_c(nT)$$

In other words, the broken sampler cannot be fixed this way!