## HOMEWORK SOLUTIONS #5

1. (a) Consider the  $k^{th}$  branch.

$$
y_k[m] \longrightarrow \boxed{f(N)} \xrightarrow{v_k[n]} \begin{array}{c} \begin{array}{c} \hline \begin{array}{c} \hline \begin{array}{c} \hline \begin{array}{c} \hline \end{array} \\ \hline \end{array} \\ \hline \begin{array}{c} \hline \begin{array}{c} \hline \end{array} \\ \hline \end{array} \\ \hline \begin{array}{c} e^{-j\frac{2\pi}{N}kn} \end{array} \end{array}} \end{array}
$$

We have

$$
x_k[n] = \left(\sum_i h[i]v_k[n-i]\right) e^{-j\frac{2\pi}{N}kn}
$$
  
= 
$$
\sum_i \underbrace{h[i]e^{-j\frac{2\pi}{N}ki}}_{h_k[i]} v_k[n-i]e^{-j\frac{2\pi}{N}k(n-i)}
$$

where we have rewritten the branch output as the convolution of a modulated filter response  $h_k[i]$  with a modulated input  $v_k[n]e^{-j\frac{2\pi}{N}kn}$ .

$$
y_k[m] \longrightarrow \underbrace{\textcircled{\texttt{f}}\,N)} \xrightarrow{v_k[n]} \underbrace{\textcircled{\texttt{x}}}_{e^{-j\frac{2\pi}{N}kn}} \longrightarrow \underbrace{H_k(z)} \longrightarrow x[n]
$$

Noting that  $v_k[n]$  is zero-valued unless n is a multiple of N, and that  $e^{-j\frac{2\pi}{N}kn}$  equals one when  $n$  is a multiple of  $N$ , we see that the modulation has no effect. Hence the block diagram can be rewritten

$$
y_k[m] \longrightarrow \boxed{\uparrow N} \xrightarrow{v_k[n]} \boxed{H_k(z)} \longrightarrow x[n]
$$

To apply the Noble identity, we must expand  $H_k(z)$  into a parallel bank of upsampled polyphase filters. Defining  $p_{\ell}[m] = h[mN + \ell]$ , we find

$$
h_k[mN + \ell] = h[mN + \ell]e^{-j\frac{2\pi}{N}k(mN + \ell)}
$$
  
\n
$$
= p_{\ell}[m]e^{-j\frac{2\pi}{N}k\ell}
$$
  
\n
$$
H_k(z) = \sum_{i=-\infty}^{\infty} h_k[i]z^{-i}
$$
  
\n
$$
= \sum_{m=-\infty}^{\infty} \sum_{\ell=0}^{N-1} h_k[mN + \ell]z^{-mN + \ell}
$$
  
\n
$$
= \sum_{\ell=0}^{N-1} z^{-\ell}e^{-j\frac{2\pi}{N}k\ell} \sum_{m=-\infty}^{\infty} p_{\ell}[m](z^N)^{-m}
$$
  
\n
$$
= \sum_{\ell=0}^{N-1} P_{\ell}(z^N)z^{-\ell}e^{-j\frac{2\pi}{N}k\ell}
$$

thus the block diagram for the  $k^{th}$  filterbank branch becomes



Realizing that the gain  $e^{-j\frac{2\pi}{N}k\ell}$  on the  $\ell^{th}$  polyphase branch is not a function of the time index, we can put it before the filter and upsampler. Combining this with the use of a Noble identity, we get the equivalent diagram below.



Recall that the previous block diagram represents the processing required by the  $k^{th}$  filterbank branch. Notice, however, that the polyphase filters  ${P_{\ell}(z)}$  and the parallel-to-serial converter are common to all branches  $k = 0, \ldots, N-1$ ; the difference between branches is determined only by the gains  $e^{-j\frac{2\pi}{N}k\ell}$  on the left of the structure. Recall also that the system output is given by the branch sum

$$
x[n] = \sum_{k=0}^{N-1} x_k[n].
$$

Rather than summing  $x_k[n]$  over k, we can sum  $w_{\ell,k}[n]$  over k (for each  $\ell$ ):

$$
w_{\ell}[n] = \sum_{k=0}^{N-1} w_{\ell,k}[m] = \sum_{k=0}^{N-1} y_k[m] e^{-j\frac{2\pi}{N}\ell k}.
$$

then apply the values  $w_{\ell}[n]$  to a single polyphase reconstruction bank. Observe that the operation is equivalent to multiplication by a DFT matrix. The result looks like the diagram on the right below.



- 2. See plots on homework assignment.
- 3. Bi-orthogonal FIR perfect reconstruction plots appear below. Plots are given for various root group allocations. In all cases, we get real-valued linear-phase perfectly reconstructing filters.







