ECE-501Introduction to Analog and Digital CommunicationsWHomework #2J

## HOMEWORK SOLUTIONS #2

1. (a) Ideal zero-phase LPF:

$$h(t) = \int_{-\infty}^{\infty} H(f) e^{j2\pi ft} df = \int_{-B}^{B} e^{j2\pi ft} df \text{ via the definition of } H(f)$$
(1)

$$= \frac{1}{j2\pi t} e^{j2\pi ft} \Big|_{f=-B}^{B} = \frac{1}{\pi t} \frac{1}{j2} \Big[ e^{j2\pi Bt} - e^{-j2\pi Bt} \Big] = \frac{1}{\pi t} \sin(2\pi Bt)$$
(2)

$$= 2B \frac{\sin(2\pi Bt)}{2\pi Bt} = 2B \operatorname{sinc}(2Bt).$$
(3)

- (b) Say H(f) is the ideal zero-phase LPF, as above. Then we can write the ideal linear-phase LPF as  $G(f) = H(f)e^{-j2\pi ft_o}$ . Since we know that  $h(t) = 2B\operatorname{sinc}(2Bt)$ , we can use the fact that  $X(f)e^{-j2\pi ft_o} \xleftarrow{\mathcal{F}} x(t-t_0)$  to claim that  $g(t) = 2B\operatorname{sinc}(2B(t-t_o))$ .
- 2. (a) Truncated-sinc LPF:



The magnitude response is not perfect in that there is ringing near the cutoff frequency.

- (b) firls-designed LPF:
  - Ts = 0.001; t\_o = 0.25; Lf = 2\*t\_o/Ts; B = 20; fp = 0.9\*B\*2\*Ts; fs = 1.1\*B\*2\*Ts; h = firls(Lf,[0,fp,fs,1],[1,1,0,0])/Ts; plottf(h,Ts);



## (c) firpm-designed LPF:



(d) fir2-designed LPF:

Ts = 0.001; t\_o = 0.25; Lf = 2\*t\_o/Ts; B = 20; fp = 0.9\*B\*2\*Ts; fs = 1.1\*B\*2\*Ts; h = fir2(Lf,[0,fp,fs,1],[1,1,0,0])/Ts; plottf(h,Ts);



- (e) The LPFs designed using the MATLAB built-in routines yield magnitude responses that are generally much closer to ideal than the truncated-sinc LPF. The passbands from firls and fir2 are very flat, that from firpm has very small ripples, while that from the truncated-sinc filter is flat except for severe ringing near the passband edge. The stopbands from firls and fir2 are essentially zero over the desired range, that of the truncated-sinc filter is also zero except near the stopband edge, while that from firpm doesn't quite reach zero, which could be problematic. The impulse responses of all the filters look pretty similar, except that the MATLAB built-in LPFs have impulse responses that decay smoothly to zero in comparison to the truncated-sinc LPF.
- 3. The original noise waveform and its LPF'ed and HPF'ed versions are shown below, along with the MATLAB code that designs and implements the filters:



The filtering works as expected: it preserves the input signal over its passband but rejects it over its stopband.

4. (a) The approximate Dirac delta and its plottf-approximated Fourier transform are:



It is encouraging to see that the frequency magnitude response matches that of  $\mathcal{F}{\delta(t)} = 1$  (over the frequency range that is plotted by plottf).

(b) The complex exponential and its plottf-approximated Fourier transform are (for  $t_{\text{max}} = 3$ ):



While the basic shape of the frequency magnitude response matches that of  $\mathcal{F}\{\exp(j2\pi f_o t)\} = \delta(f - f_o)$ , it is impossible to actually plot  $\delta(f - f_o)$  due to its infinite height.

(c) The complex exponential and its plottf-approximated Fourier transform are (for  $t_{\text{max}} = 5$ ):



The difference between the case  $t_{\text{max}} = 5$  and  $t_{\text{max}} = 3$  is that the height of the spike is now 5 rather than 3. It is interesting that changing the *length* of the time-domain waveform changes the *amplitude* in the frequency domain. This behavior can be traced back to equations (1)-(2) on the homework, which show how the FT is approximated by **plottf**: as  $t_{\text{max}}$  increases, so does the number of samples N, which causes the sum in (2) to grow proportionally.