ECE-501Introduction to Analog and Digital CommunicationsWinter 2008Homework #1Jan. 9, 2008

## HOMEWORK SOLUTIONS #1

1. This problem can be solved using the inverse FT definition and Euler's representation of a cosine:

$$g(t) = \int_{-\infty}^{\infty} G(f) e^{j2\pi ft} df$$
(1)

$$= \int_{-W}^{0} e^{j\pi/2} e^{j2\pi ft} df + \int_{0}^{W} e^{-j\pi/2} e^{j2\pi ft} df$$
(2)

$$= j \left[ \frac{1}{j2\pi t} e^{j2\pi ft} \right]_{f=-W}^{0} - j \left[ \frac{1}{j2\pi t} e^{j2\pi ft} \right]_{f=0}^{W}$$
(3)

$$= \frac{1}{2\pi t} \left[ 1 - e^{-j2\pi Wt} \right] - \frac{1}{2\pi t} \left[ e^{j2\pi Wt} - 1 \right]$$
(4)

$$= \frac{1}{\pi t} - \frac{1}{2\pi t} \left[ e^{j2\pi Wt} + e^{-j2\pi Wt} \right]$$
(5)

$$= \frac{1}{\pi t} \left[ 1 - \cos(2\pi W t) \right] \tag{6}$$

2. From p. 28 of the text, we know that  $\mathcal{F}\{g^*(t)\} = G^*(-f)$ . If you don't want to memorize this, it's easy to derive:

$$\mathcal{F}\{g^*(t)\} = \int g^*(t)e^{-j2\pi tf}dt = \left[\int g(t)e^{j2\pi tf}dt\right]^* = \left[\int g(t)e^{-j2\pi t(-f)}dt\right]^* = G^*(-f)$$
(7)

Now, for a real-valued g(t), we know that  $g(t) = g^*(t)$ , which implys that  $G(f) = G^*(-f)$ . Taking the absolute value, we see that that latter implies |G(f)| = |G(-f)|.

3. We would like to use

$$\int_{-\infty}^{\infty} g_1(\tau)g_2(t-\tau)d\tau \quad \stackrel{\mathcal{F}}{\longleftrightarrow} \quad G_1(f)G_2(f) \tag{8}$$

to prove

$$\int_{-\infty}^{\infty} g_1(t)g_2^*(t-\tau)dt \quad \stackrel{\mathcal{F}}{\longleftrightarrow} \quad G_1(f)G_2^*(f).$$
(9)

One way to do this is to notice that if  $g_2(t) = g_3^*(-t)$ , then

$$G_2(f) = \int g_3^*(-t)e^{-j2\pi tf}dt = \left[\int g_3(-t)e^{j2\pi tf}dt\right]^* = \left[\int g_3(\tau)e^{-j2\pi \tau f}d\tau\right]^* = G_3^*(f).$$
(10)

Applying  $g_2(t) = g_3^*(-t)$  and (10) to (8), we get

$$\int_{-\infty}^{\infty} g_1(\tau) g_3^*(\tau - t) d\tau \quad \stackrel{\mathcal{F}}{\longleftrightarrow} \quad G_1(f) G_3^*(f), \tag{11}$$

which is equivalent to (9).

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4. (a) To find  $\mathcal{F}\{\cos^2(2\pi f_c t)\}\)$ , we can apply the Euler identity  $\cos(2\pi f_c t) = \frac{1}{2} \left[ e^{j2\pi f_c t} + e^{-j2\pi f_c t} \right]$ and then leverage  $\mathcal{F}\{e^{j2\pi f_o t}\} = \delta(f - f_o)$  and the linearity property:

$$\cos^2(2\pi f_c t) = \frac{1}{4} \left[ e^{j2\pi f_c t} + e^{-j2\pi f_c t} \right]^2 = \frac{1}{4} \left[ e^{j2\pi 2f_c t} + 2 + e^{-j2\pi 2f_c t} \right]$$
(12)

$$\Rightarrow \mathcal{F}\{\cos^2(2\pi f_c t)\} = \frac{1}{4}\delta(f - 2f_c) + \frac{1}{2}\delta(f) + \frac{1}{4}\delta(f + 2f_c)$$
(13)

(b) To find  $\mathcal{F}\{\sin^2(2\pi f_c t)\}\)$ , we do the same thing with the Euler identity  $\sin(2\pi f_c t) = \frac{1}{2j} \left[e^{j2\pi f_c t} - e^{-j2\pi f_c t}\right]$ 

$$\sin^2(2\pi f_c t) = -\frac{1}{4} \left[ e^{j2\pi f_c t} + e^{-j2\pi f_c t} \right]^2 = -\frac{1}{4} \left[ e^{j2\pi 2f_c t} - 2 + e^{-j2\pi 2f_c t} \right]$$
(14)

$$\Rightarrow \mathcal{F}\{\sin^2(2\pi f_c t)\} = -\frac{1}{4}\delta(f - 2f_c) + \frac{1}{2}\delta(f) - \frac{1}{4}\delta(f + 2f_c)$$
(15)